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## **ACTIVE TESTING SURVEILLANCE SYSTEMS, OR,** PLAYING TWENTY QUESTIONS WITH A RADAR

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Department of Electrical Engineering Washington University in St. Louis

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#### CONTEXT

Airborne multisensor pulse-Doppler surveillance radar

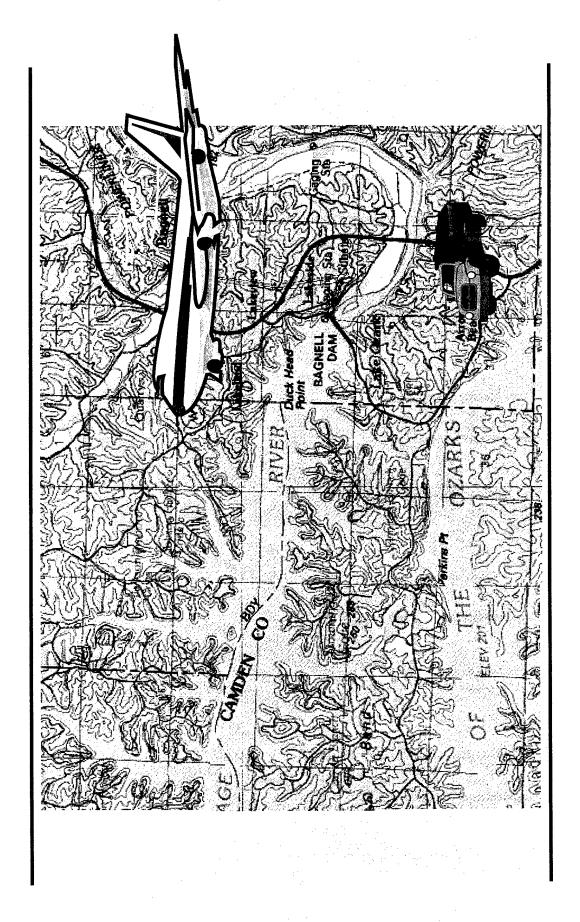
Ground moving targets (GMTI)

Multiple targets

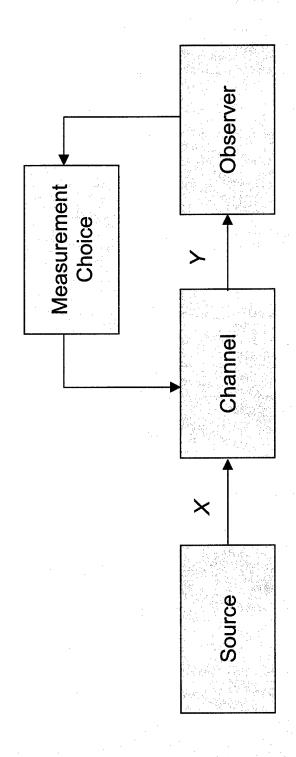
Geographical side information (GIS)

Platform side information (GPS, INS)

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# **ACTIVE-TESTING SURVEILLANCE SYSTEM**



the added feature that the channel can be manipulated by the observer. A communication system in the usual information-theoretic sense, with

## **GENERAL APPROACH**

The goal of a surveillance system is to minimize the entropy of the posterior distribution of the source vector X.

Entropy definition:

$$H(X) = -\sum_{x} p_X(x) \log_2 p_X(x)$$

Conditional entropy definition:

$$H(X|Y) = -\sum_{y} p_Y(y) \sum_{x} p_{X|Y}(x|y) \log p_{X|Y}(x|y)$$
$$= -\sum_{y} \sum_{x} p_{XY}(x,y) \log p_{X|Y}(x|y)$$

## SINGLE-MEASUREMENT STRATEGY

Choose that measurement which maximizes the mutual information I(X, Y)

Mutual information definition:

$$I(X,Y) = H(X) - H(X|Y)$$
$$= H(Y) - H(Y|X)$$

obvious and intuitive, but is "greedy" and may not be globally optimal Repeated measurements: maximizing I(X, Y) at each step seems

### **TWENTY QUESTIONS**

- A game in which the objective is to determine the correct answer by asking the right questions in the right order.
- Perhaps "Battleship" or "Mastermind" is a better analogy, since there is more feedback from observation to question.
- like Shannon-Fano coding. The globally optimum code is the Huffman the answer to a YES/NO set membership question. We like each bit to be maximally informative. If the bits are determined sequentially this is Connection with source coding: in binary coding, each bit represents

# SAMPLING OF RELEVANT LITERATURE

Sequential detection: Berger (1980)

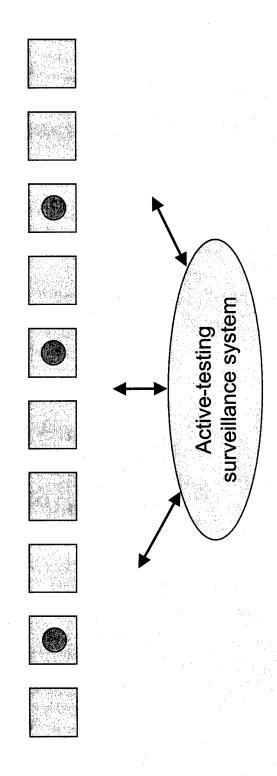
Experimental design: Carlin and Louis (1996)

Coding theory connection: Goodman and Smyth (1988)

Selection of maximally informative measurement:

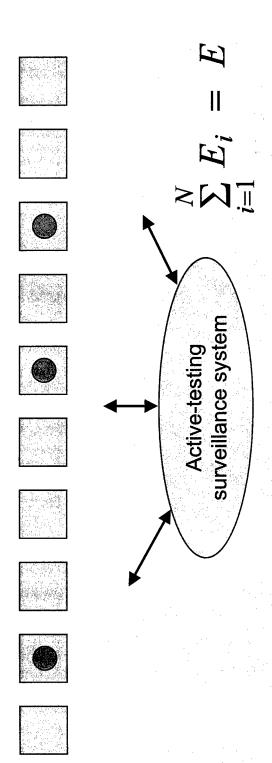
Lewis (1962)
Pearl (1988)
Geman and Jedynak (1996)
Yuille and Coughlan (2000)

# **MULTIPLE TARGET DETECTION SCENARIO**



- N independent cells
- Each cell defines a binary hypothesis testing problem
- Divergence between H0 and H1 depends on transmitted energy

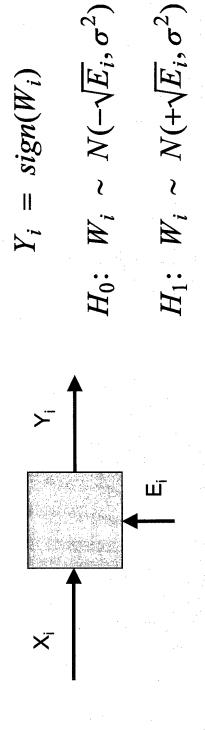
## **FINITE-ENERGY CONSTRAINT**



· What is the optimum partition of the available energy E?

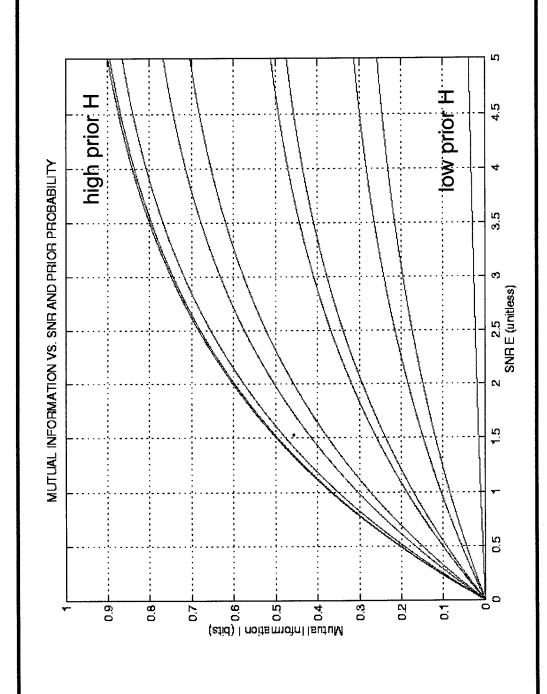
### SIMPLE DATA MODEL

• Each cell acts like a binary symmetric channel (BSC):



$$P_{e,i} = 1 - \Phi\left(\frac{\sqrt{E_i}}{\sigma}\right)$$

## FAMILY OF I(X,Y) vs. SNR CURVES



# **OPTIMIZATION OF ENERGY PARTITION**

Optimization problem:

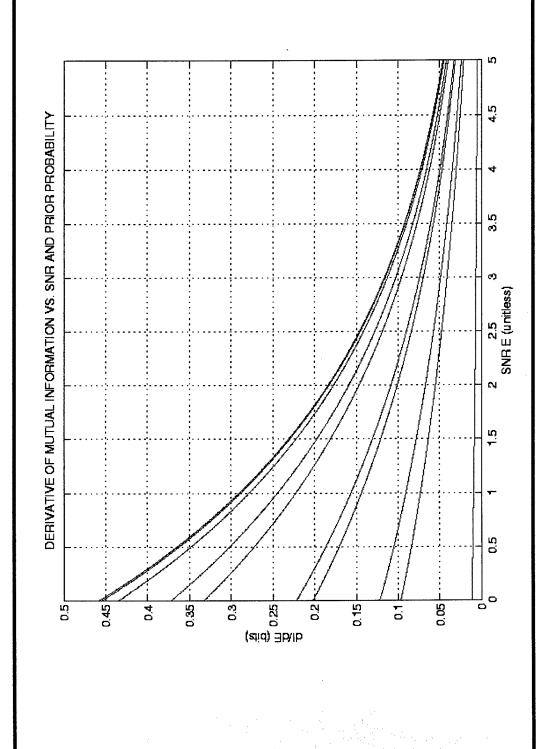
$$\max_{\{E_i\}} \sum_{i=1}^{N} I(X_i, Y_i; p_i, E_i) \quad \text{s.t.} \sum_{i=1}^{N} E_i = E$$

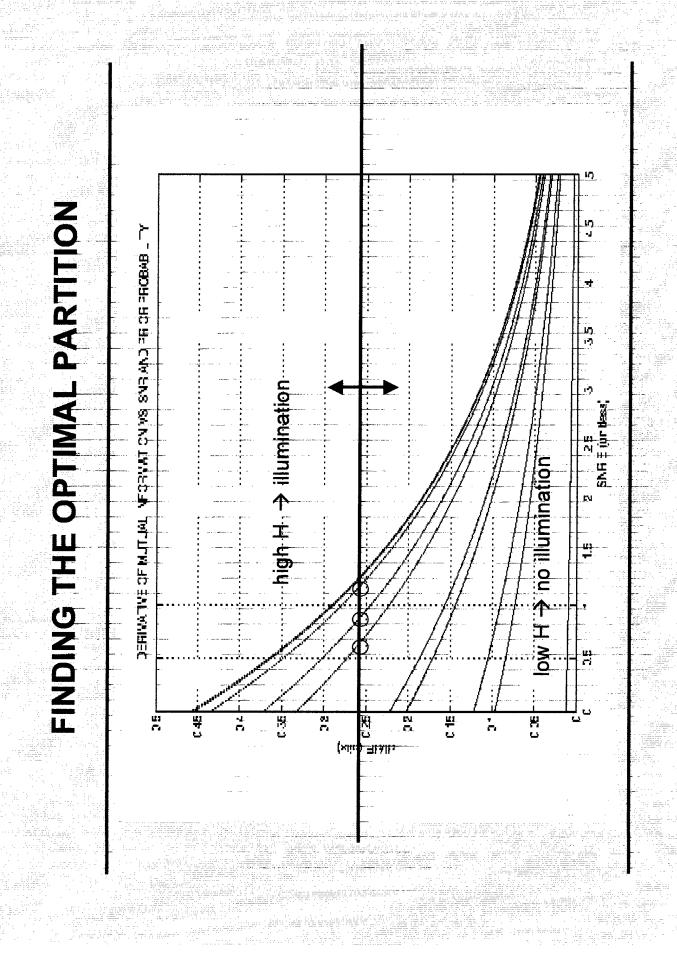
Kuhn-Tucker conditions:

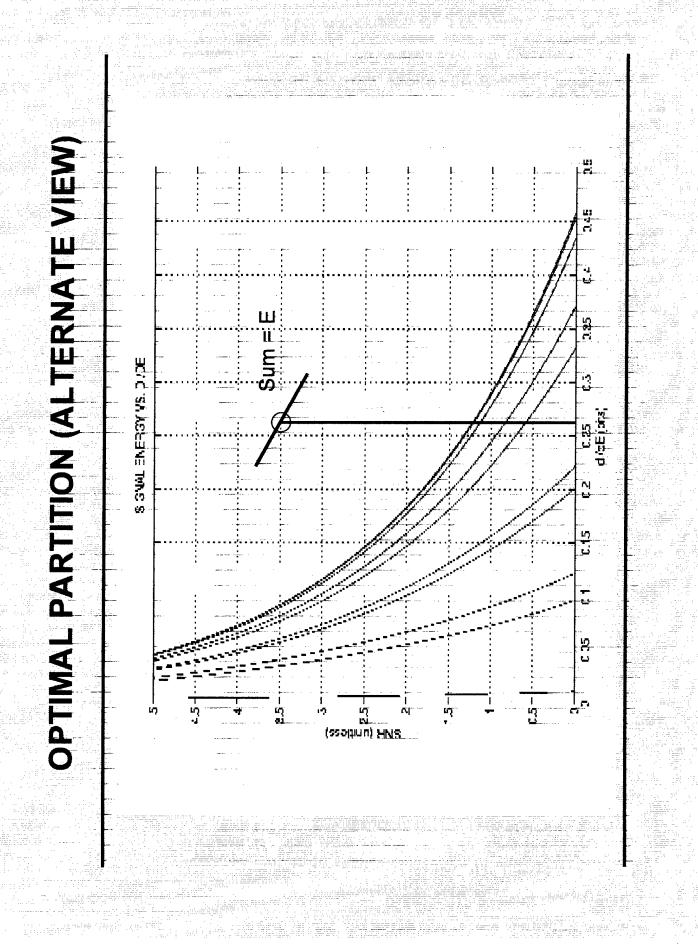
If 
$$E_i \neq 0$$
, then  $\frac{\partial I}{\partial E_i} = \lambda$ 

If 
$$\frac{\partial I}{\partial E_i} < \lambda$$
, then  $E_i = 0$ 

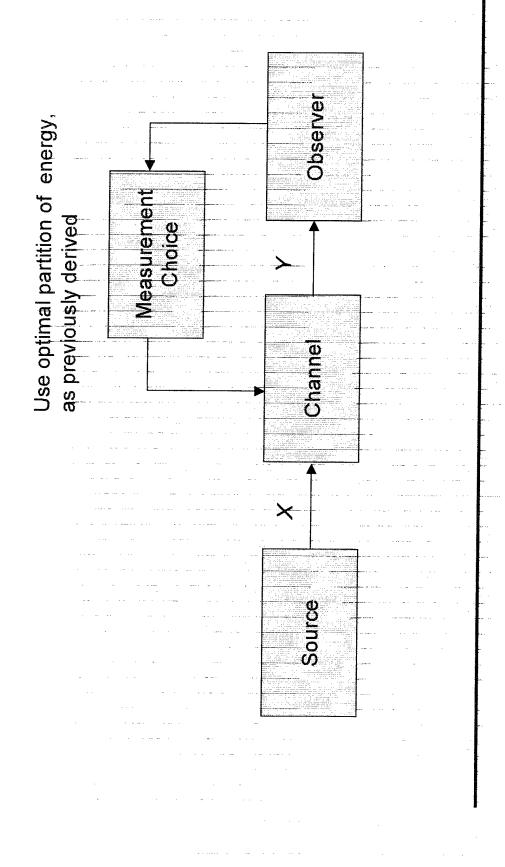
## FAMILY OF dI/dE CURVES







## **ACTIVE TESTING, AGAIN**



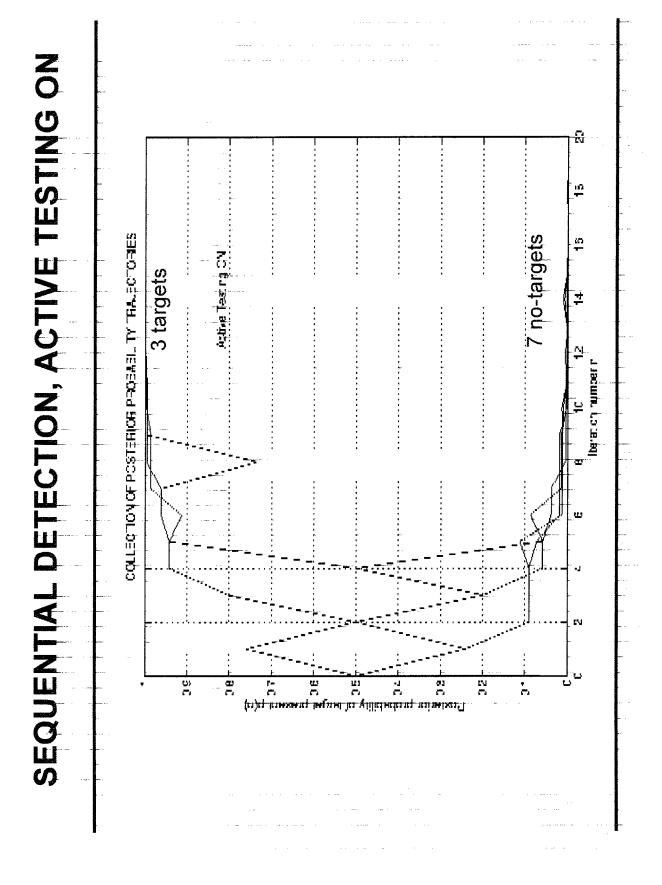
### SIMULATION SET-UP

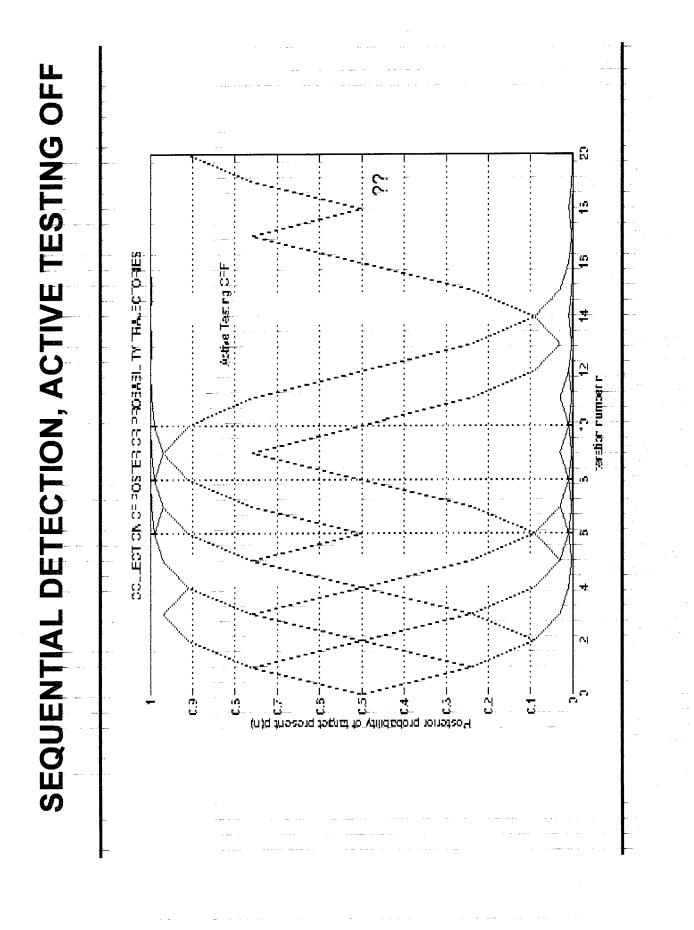
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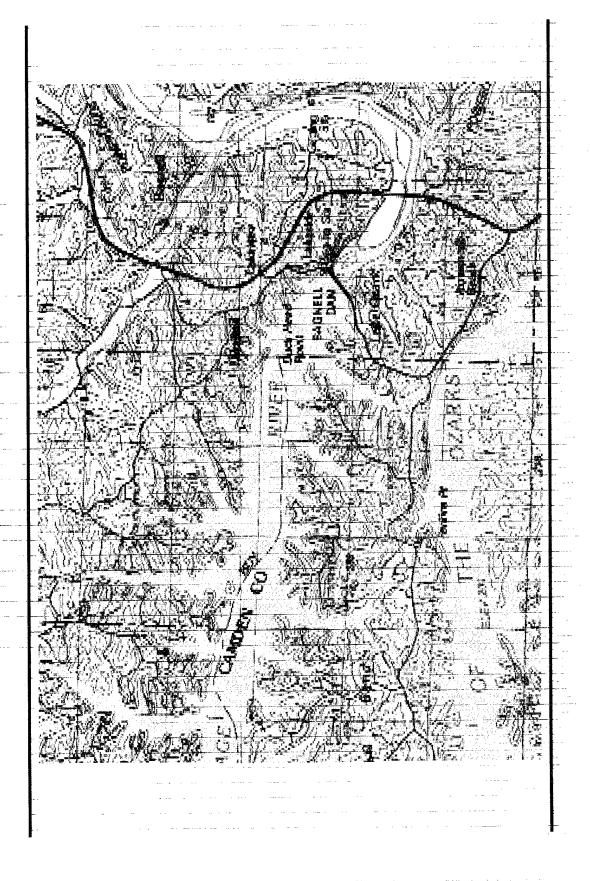
Active-testing surveillance system







## WHERE DO WE GO FROM HERE?



#### RESEARCH AIM

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#### MMEDIATE GOALS

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Allow different clutter and target signatures in cell (targets are moving

Include adaptive processing for interference

#### CONCLUSION

#### We have:

- ntroduced the concept of active-testing surveillance systems
- considered multiple-target detection
- derived numerical solution to optimization problem of distribution of finite illumination energy
- shown anecdotal result that active testing improves convergence in sequential detection
- indicated future research directions in airborne multisenso oulse-Doppler surveillance radar